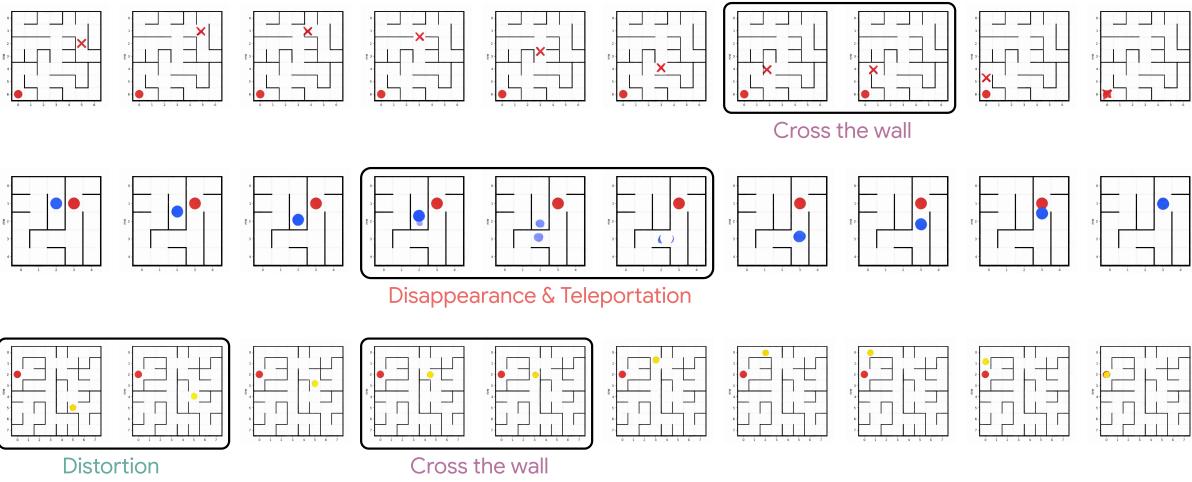

Thinking in Frames: How Visual Context and Test-Time Scaling Empower Video Reasoning

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Ruichuan An ⁵ Dengyang Jiang ⁶ Zhaochong An ² Ivan Vulić ¹ Serge Belongie ² Anna Korhonen ¹

Seen Icons During Training



Unseen Icons

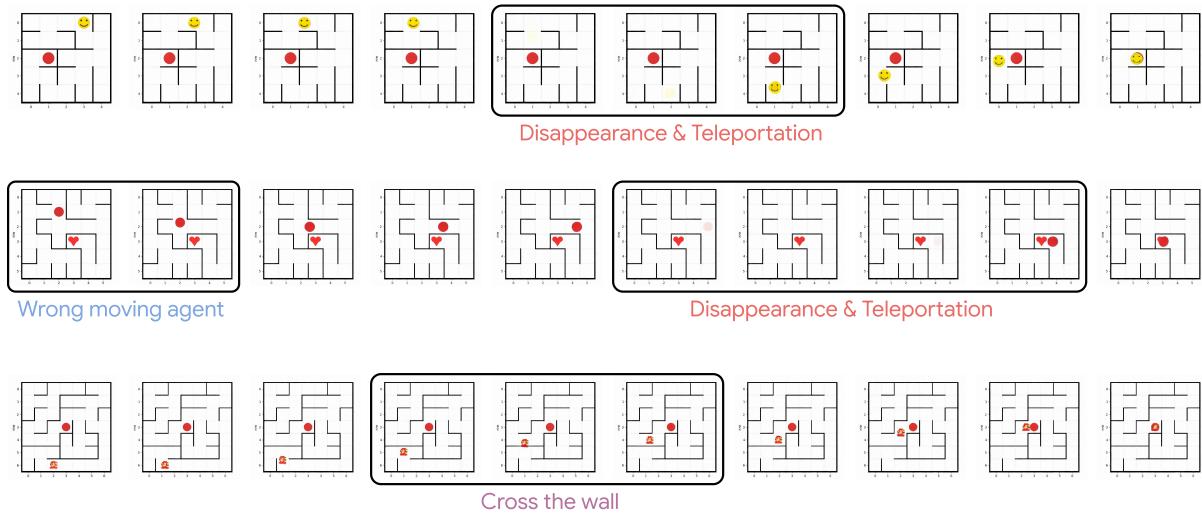
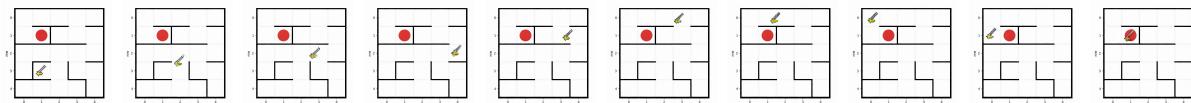


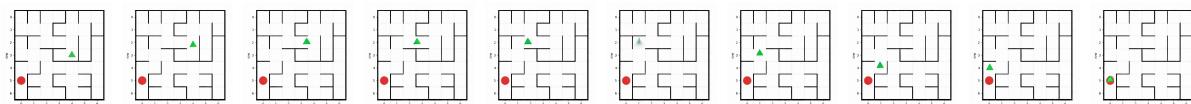
Figure 1. Wrong examples of MAZENAVIGATION generated by fine-tuned Wan 2.2 TI2V 5B.

Seen Icons During Training

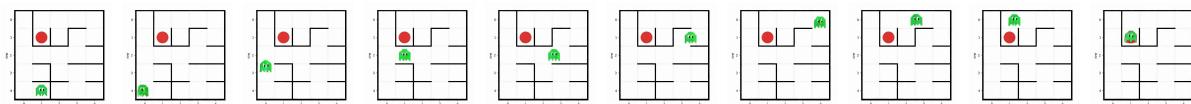
In-Distribution Maze Size & Path Length



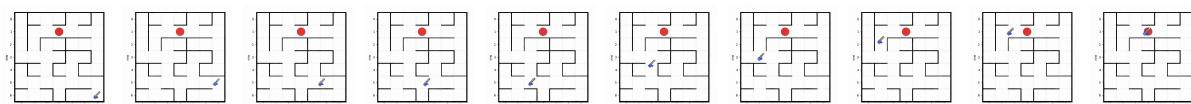
OOD Maze Size



OOD Path Length

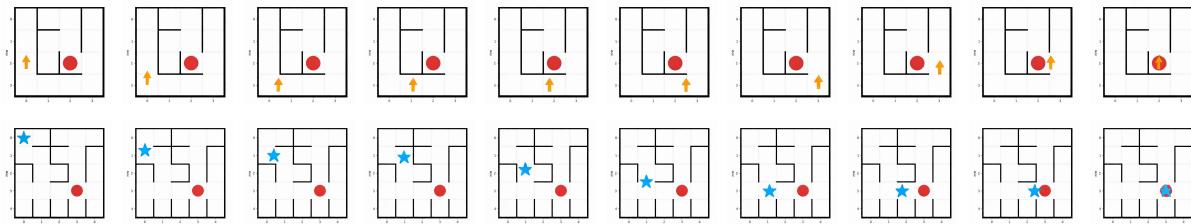


OOD Both

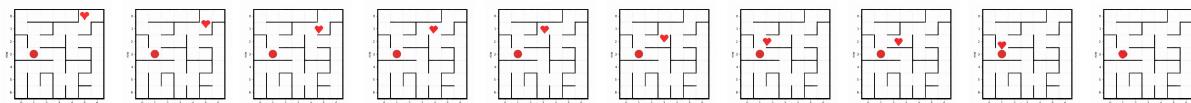


Unseen Icons

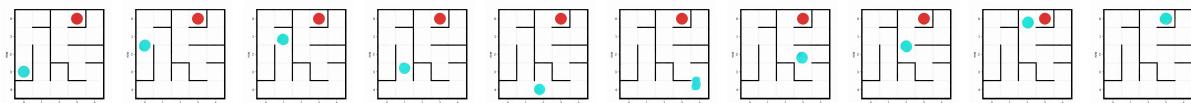
In-Distribution Maze Sizes & Path Length



OOD Maze Size



OOD Path Length



OOD Both

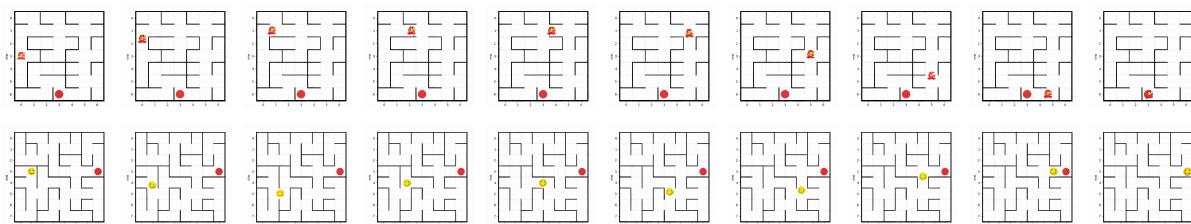
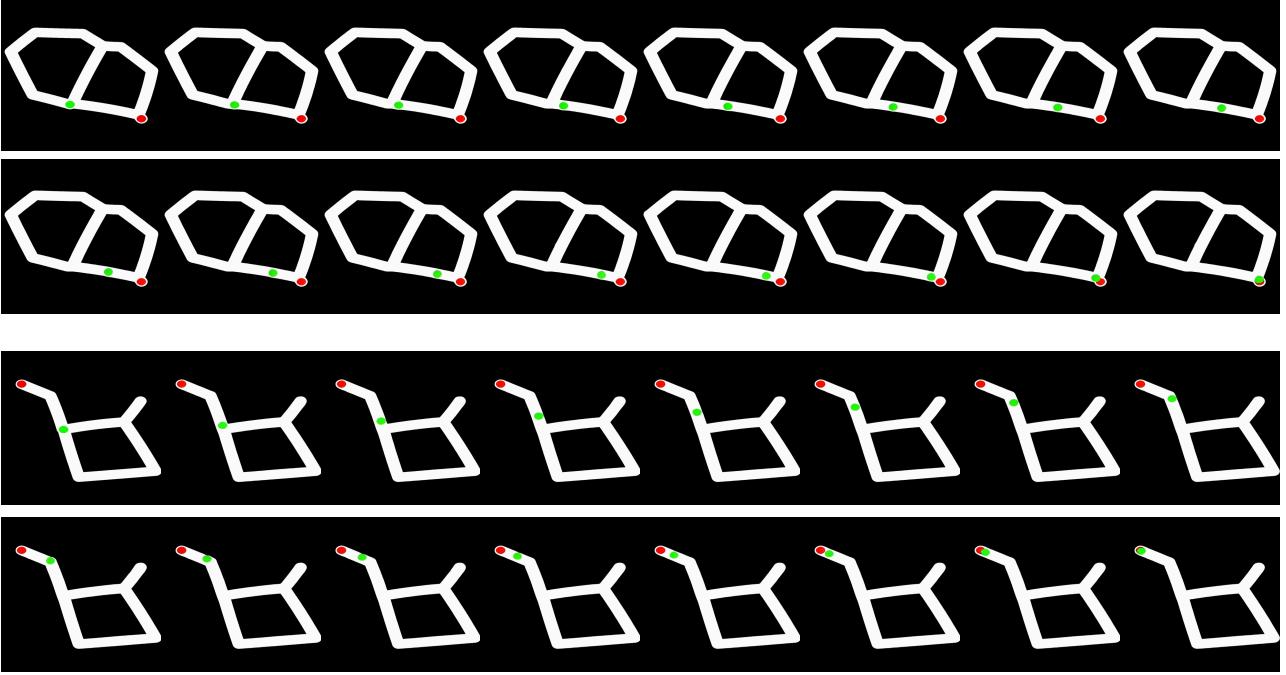


Figure 2. Correct examples of MAZENAVIGATION generated by fine-tuned Wan 2.2 TI2V 5B.

Zero-Shot Inference on Irregular Mazes

Success Case



Failure Case

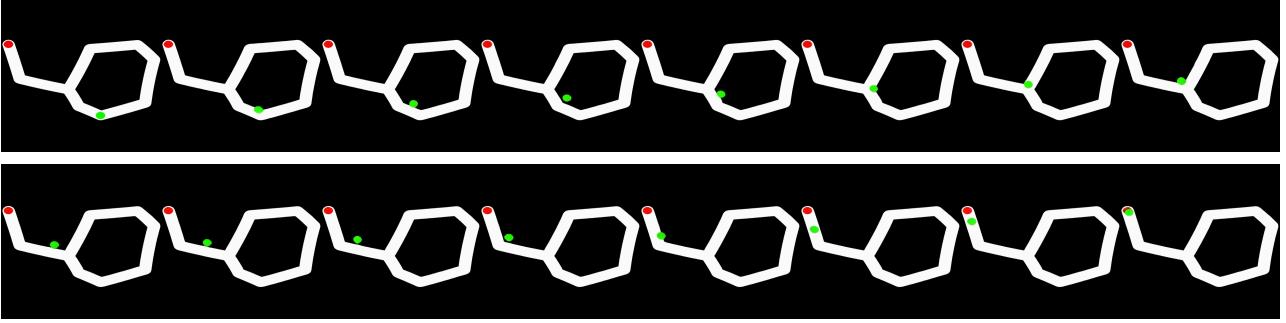


Figure 3. Visualizations of zero-shot inference on irregular maze with Wan 2.2 TI2V 5B trained on regular mazes. We observe that although not included in the training data, trained video generation model can adapt a certain level of planning capabilities to such irregular mazes with different background and meanwhile keeping the constraint (no change in the background, follow the path, do not cross the wall), and surprisingly can move diagonally.

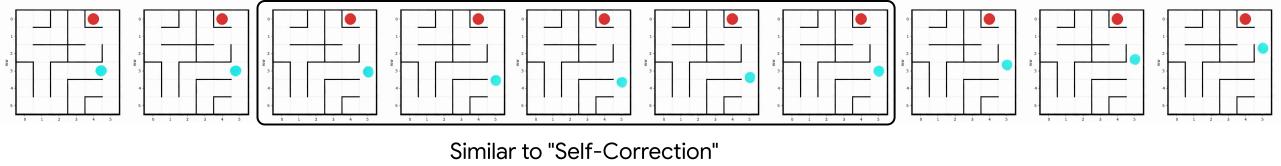


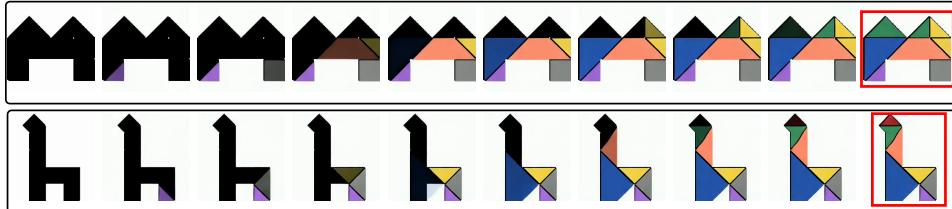
Figure 4. Example of trajectory similar to “self-correction” in MAZENAVIGATION when provided with more inference frame budget.

Fade-In

Qwen Image Edit 2509



Wan 2.2 TI2V 5B

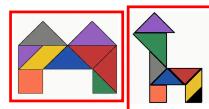


Rotation

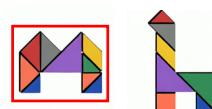
Qwen-VL



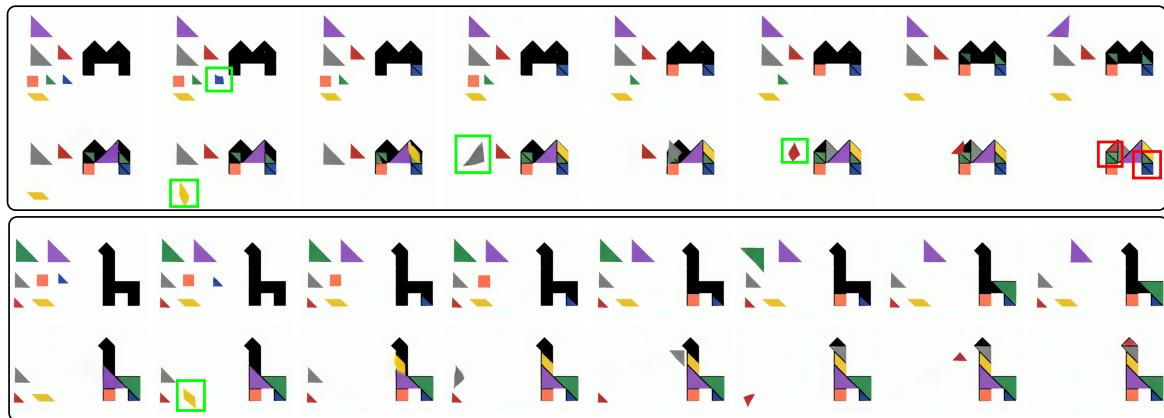
Nano Banana



Qwen Image Edit 2509

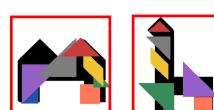


Wan 2.2 TI2V 5B



Translation

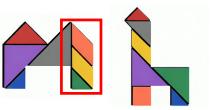
Qwen-VL



Nano Banana



Qwen Image Edit 2509



Wan 2.2 TI2V 5B

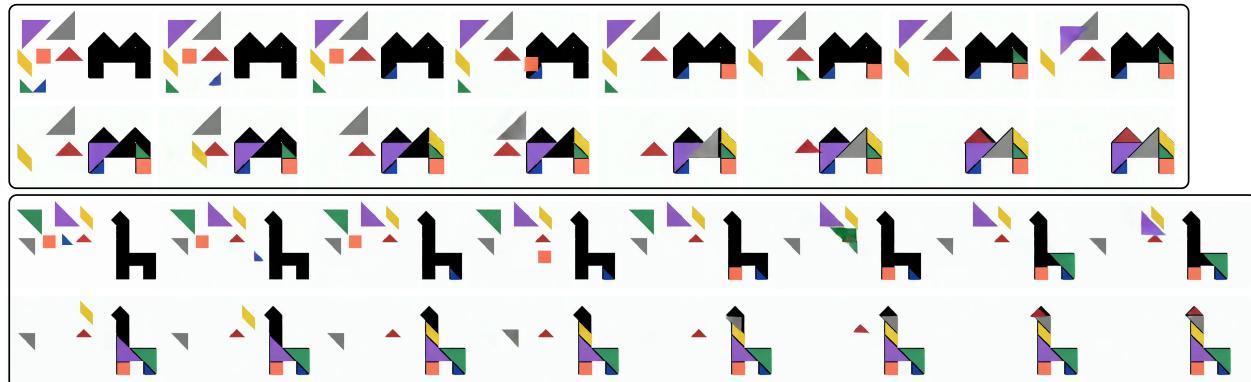


Figure 5. Examples of TANGRAMPUZZLE generated by different systems. Red bounding boxes indicates wrong predictions, and green bounding box indicates distortion throughout the process.